

This procedure simplifies I/O interconnections. Let's say robot input 1 needs to be sent to an external device using Digital output 25. Here's how to map these I/O together.

- 1** PRESS --> **[I/O]**
- 2** PRESS --> **[F1]** [TYPE]
- 3** SELECT --> **[9]** 9 INTERCONNECT
- 4** PRESS --> **[ENTER]**
- 5** PRESS --> **[F3]** [SELECT]
- 6** SELECT --> **[1]** 1 RI -> DO (*8 interconnections of this kind can be mapped.*)
- 7** PRESS --> **[ENTER]**
- 8** Using Arrow on line 1 --> Move cursor to the "**Output**" column.
- 9** ENTER --> **25**
- 10** PRESS --> **[ENTER]**
- 11** Using Arrow on line 1 --> Move back cursor to the "**Enb/Disabl**" column.
- 12** PRESS --> **[F4]** ENABLE
- 13** Explore the Interconnect menu to see more available features.