You have to determine the "The zone" for which you want to set a cartesian position check. Let's say, for example you want to set up a cartesian position check for the electrical panel of the cell. The purpose of the cartesian position check is to protect the electrical panel from the robot.

1 PRESS --> [ MENU ]

2 SELECT -->[0] 0 NEXT

3 SELECT -->[6]6 SYSTEM

4 SELECT -->[7]7DCS

5 Using arrow --> Scroll down to line 3 : Cart. Position check

6 PRESS --> [ NEXT ] Press [NEXT] until you see F3 key as DETAIL

7 PRESS --> [ F3] DETAIL

8 Using Arrow --> Scroll down to an empty Cartesian position check that is not defined Let's say line 4.

9 PRESS --> [ F3] DETAIL

10 At line 2, PRESS --> [ ENTER ]

11 ENTER --> A comment like : Panel

12 At line 3, PRESS --> [ F4] [ CHOICE ]

13 SELECT --> [ 2 ] 2 Restricted zone (Diagonal). (this will set a rectangular prism where the robot will not have access.)

14 At line 8, ENTER --> $\mathbf{0}$ (to set the rectangular zone reference to the World frame.)

15 At line 9,10 and 11, ENTER --> The coordinates of the two points of the diagonal, which reference is the world frame. according to which the rectangular prism et located in space.

16 At line 12, PRESS --> [ F4][CHOICE ]

17 SELECT --> [ 1 ] 1 Stop Category 0 (This will set the robot to stop its motors immediately.)

18 At line 2, PRESS --> [ ENTER ]

19 If the question "Do you want to change the settings?" is asked, PRESS --> [ F4 ] YES

20 PRESS --> [F4][CHOICE ]
(21)PRESS -->[2]2 ENABLE

22 PRESS --> [ PREV ]

23 PRESS -->[ PREV ]

24 PRESS --> [ F2 ] APPLY

25 ENTER --> Code number (master): $\mathbf{x x x x}$ (Refer to Robot cell integrator for code.)

26 PRESS -->[F4]OK

27 PRESS --> [ FCTN ]

28 SELECT -->[0]0 NEXT

29 SELECT -->[8] 8 CYCLE POWER

30 PRESS --> [YES ]

31 The DCS set up will be added to the one already in function.

