DIY-ROBOTICS TUTORIALSetting up a DCS – Cartesian position check



You have to determine the "The zone" for which you want to set a cartesian position check. Let's say, for example you want to set up a cartesian position check for the electrical panel of the cell. The purpose of the cartesian position check is to protect the electrical panel from the robot.

- PRESS --> [MENU]
- SELECT --> [0] 0 NEXT
- SELECT --> [6] 6 SYSTEM
- 4 SELECT -->[7]7DCS
- Using arrow --> Scroll down to **line 3 : Cart**. Position check
- 6 PRESS --> [NEXT] Press [NEXT] until you see F3 key as DETAIL
- PRESS --> [F3] DETAIL
- Using Arrow --> Scroll down to an empty Cartesian position check that is not defined Let's say line 4.
- PRESS --> [F3] DETAIL
- 10 At line 2, PRESS --> [ENTER]
- 11 ENTER --> A comment like: Panel
- At line 3, PRESS --> [F4] [CHOICE]

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- SELECT --> [2] 2 Restricted zone (Diagonal). (this will set a rectangular prism where the 13 robot will not have access.)
- 14 At line 8, ENTER --> **0** (to set the rectangular zone reference to the World frame.)
- At line 9, 10 and 11, ENTER --> The coordinates of the two points of the diagonal, which 15 reference is the world frame. according to which the rectangular prism et located in space.
- 16 At line 12, PRESS --> [**F4**] [CHOICE]
- SELECT --> [1] 1 Stop Category 0 (This will set the robot to stop its motors immediately.)
- 18 At line 2, PRESS --> [ENTER]
- 19 If the question "Do you want to change the settings?" is asked, PRESS --> [F4] YES
- 20 PRESS --> [**F4**] [CHOICE]
- PRESS --> [2] 2 ENABLE
- PRESS --> [PREV]
- PRESS --> [PREV]
- PRESS --> [**F2**] APPLY

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- ENTER --> **Code number (master): xxxx** (Refer to Robot cell integrator for code.)
- 26 PRESS --> [**F4**] OK
- PRESS --> [FCTN]
- SELECT -->[0]0 NEXT
- SELECT --> [8] 8 CYCLE POWER
- 30 PRESS -->[YES]
- 31 The DCS set up will be added to the one already in function.